

Using Eqs. (4) and (5) together with Eqs. (2) and (3), the unknown vortex strengths  $a$  and  $b$  can be found to be

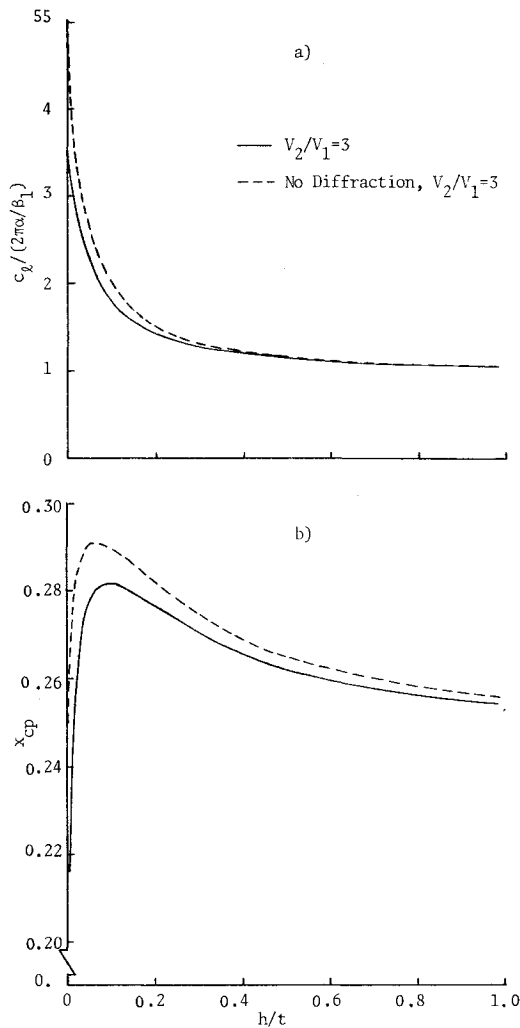


Fig. 3 Aerodynamic characteristics of a flat-plate airfoil with jet interaction in incompressible flow.  $t/c = 0.5$ .

$$a = -\Gamma_1 \left( \frac{\rho_2 V_2^2}{\rho_1 V_1^2} - \frac{\beta_2}{\beta_1} \right) / \left( \frac{\rho_2 V_2^2}{\rho_1 V_1^2} + \frac{\beta_2}{\beta_1} \right) = \lambda_{12} \Gamma_1 \quad (6)$$

$$b = \Gamma_1 \left( 2 \frac{V_2}{V_1} \right) / \left( \frac{\rho_2 V_2^2}{\rho_1 V_1^2} + \frac{\beta_2}{\beta_1} \right) = \delta_{12} \Gamma_1 \quad (7)$$

Equations (6) and (7) show that the parameters determining the additional vortex strength "a" of the reflected disturbances and the vortex strength "b" for the diffracted disturbances are the dynamic pressure ratio, the velocity ratio and the  $\beta$  ratio. In incompressible flow, Eqs. (6) and (7) agree with those given by Koning.<sup>3</sup>

Now apply the above results to the configuration shown in Fig. 1. Define  $z_1$  and  $z_2$  as the distances from the lower and upper jet boundaries,  $B_1$  and  $B_2$ , respectively. The distance will be regarded as positive if the vortex is above the boundary. The reflection of disturbances from region 2 into region 1 is characterized by the reflection coefficient  $\lambda_{12}$  which is equal to  $a/\Gamma_1$  of Eq. (6) and the diffraction from region 1 into region 2 by  $\delta_{12}$  which is equal to  $b/\Gamma_1$  of Eq. (7). Similar definitions can also be applied to define  $\lambda_{21}$  and  $\delta_{21}$  by interchanging the subscripts 1 and 2 in Eqs. (6) and (7). Now a vortex  $\gamma$  at a distance  $h$  from  $B_1$  (or  $z_1 = -h$ ) is reflected at  $B_1$ , with an additional vortex  $\lambda_{12}\gamma$  at  $z_1 = +h$  and diffracted into the midstream with a vortex  $\delta_{12}\gamma$  at  $z_1 = -\beta_1 h/\beta_2$ . The diffracted disturbance is then reflected at  $B_2$  to give an additional vortex  $\delta_{12}\lambda_{21}\gamma$  at  $z_2 = \beta_1 h/\beta_2 + t$ . The reflected disturbances are in turn reflected and diffracted at  $B_1$ . The diffracted disturbances into the lower region are due to the vortex  $\delta_{12}\lambda_{21}\delta_{21}\gamma$  at  $z_1 = (\beta_1 h/\beta_2 + 2t) \beta_2/\beta_1 = h + 2t\beta_2/\beta_1$ , and so on. Adding the

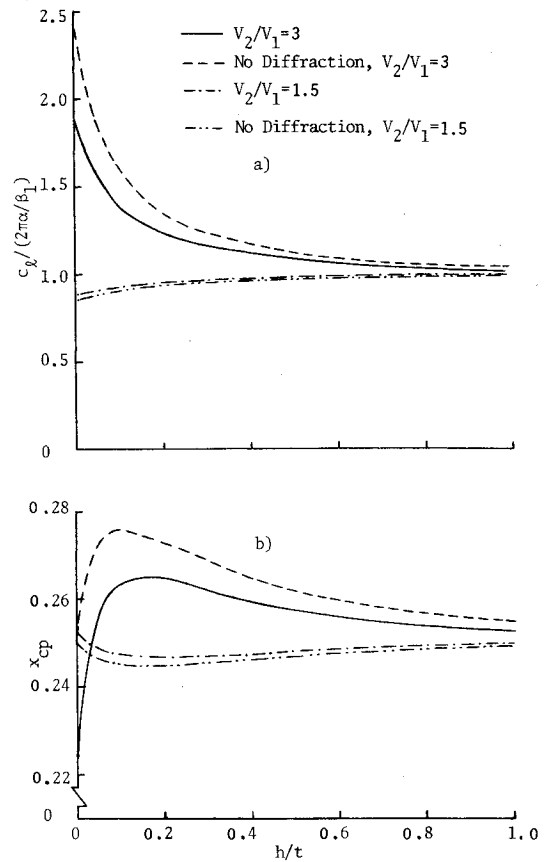


Fig. 4 Aerodynamic characteristics of a flat-plate airfoil with jet interaction in linearized compressible flow.  $t/c = 0.5$ ,  $M_1 = 0.4$ , and  $T_2/T_1 = 3$ .

effects of all image vortices in the upper stream gives the total diffracted disturbances in the lower stream. With reference to the airfoil coordinate system, the downwash produced at the airfoil is given by

$$w(x, 0) = -\frac{\beta_1}{2\pi} \int_0^1 \left\{ \frac{1}{x-x'} + \frac{\lambda_{12}(x-x')}{(x-x')^2 + \beta_1^2 4h^2} \right. \\ \left. + \delta_{12}\delta_{21}\lambda_{21} \sum_{i=1}^{\infty} \frac{\lambda_{21}^{2i-2}(x-x')}{(x-x')^2 + 4\beta_1^2(h + it\beta_2/\beta_1)^2} \right\} \gamma(x') dx' \quad (8)$$

where the downwash is normalized with respect to  $V_1$  and all lengths are based on the chord length. The second term inside the integral of Eq. (8) will be called the reflection term and the last the diffraction terms. The boundary condition is

$$w(x, 0) = dzc/dx - \alpha. \quad (9)$$

To solve Eqs. (8) and (9), the classical airfoil method of Ref. 2 is used and its computer program revised for the present purpose.<sup>4</sup>

#### Numerical Results and Discussions

For completeness and for comparison purposes, one set of incompressible results is presented in Fig. 3 for  $t/c = 0.5$ . For the linearized compressible flow,  $T_2/T_1 = 3$  and  $M_1 = 0.4$  were assumed. The Mach number ratio and the density ratio are computed as  $(M_2/M_1)^2 = (V_2/V_1)^2(T_1/T_2)$  and  $\rho_2/\rho_1 = T_1/T_2$ . The results are shown in Fig. 4. Figure 5 shows how the Mach number nonuniformity affects the aerodynamic characteristics. From the numerical results presented, the following observations can be made. Note that the "no diffraction" curves are the case where all diffraction terms in Eq. (8) are ignored.

1) From Figs. 3a and 4a, it is seen that the reflection coefficient  $\lambda_{12}$  is the primary parameter which determines

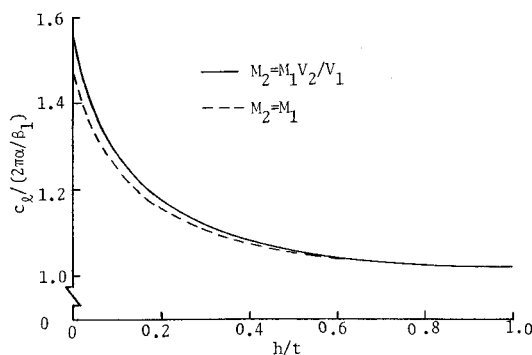


Fig. 5 Effect of Mach number nonuniformity on lift augmentation of a flat-plate airfoil.  $t/c = 0.5$ ,  $M_1 = 0.4$ ,  $T_2/T_1 = 1.0$ , and  $V_2/V_1 = 1.5$ .

the aerodynamic characteristics in the airfoil-jet interaction in either compressible or incompressible flow. A negative value of  $\lambda_{12}$  increases  $c_l$ . For example, in Fig. 4 for  $T_2/T_1 = 3$  and  $M_1 = 0.4$ ,  $\lambda_{12} = -0.5845$  for  $V_2/V_1 = 3$  and  $\lambda_{12} = 0.1542$  for  $V_2/V_1 = 1.5$ . A positive  $\lambda_{12}$  yields lower lift. Therefore, for a given jet thickness ratio  $t/c$ , it may be possible to use  $\lambda_{12}$  to correlate the experimental data with jet interaction.

2) With positive lift augmentation as represented by  $c_l/(2\pi\alpha/\beta_1) > 1$ , Figs. 3b and 4b show that the aerodynamic interaction tends to shift the c.p. backward until the airfoil is close to the jet surface. It may also be concluded that diffracted disturbances tend to move the c.p. forward and reflected disturbances would move the c.p. in the opposite direction. Since the diffraction terms are important as the airfoil gets closer to the jet boundary, this explains why the c.p. will shift rapidly forward as the airfoil is moved toward the jet boundary. Since for a flat airfoil the locations of c.p. and a.c. coincide, it is seen that for the airfoil at the jet lower surface as in the upper surface blowing configuration, the a.c. will be shifted forward of  $c/4$  point because of the interaction, a conclusion consistent with experimental results for a wing-body half model.<sup>5</sup> The shift is greater in incompressible flow than in compressible flow as seen from Figs. 3b and 4b.

3) For a given  $t/c$ , the higher the jet dynamic pressure relative to the freestream value, the faster the decrease in lift augmentation as  $h/t$  is increased. This means that raising the jet slightly above the airfoil surface would greatly decrease the lift augmentation for a high dynamic pressure jet.

4) Figure 5 shows that the lift is slightly increased for the higher jet Mach number with other parameters remaining unchanged. This fact can be explained by the more negative reflection coefficient. For  $T_2/T_1 = 1.0$ ,  $V_2/V_1 = 1.5$ , and  $M_1 = M_2 = 0.4$ ,  $\lambda_{12}$  can be computed to be  $-0.3846$ . On the other hand, if  $M_2 = M_1(V_2/V_1) = 0.6$ , then  $\lambda_{12} = -0.4410$ . More negative reflection coefficient implies more lift. The lift increment is slight because the diffraction terms which are to decrease the lift are also increased. Since  $\lambda_{12}$  remains to be  $-0.3846$  even if  $M_1 = M_2 = 0$ , the above results indicate that the lift augmentation, expressed as  $c_l/(2\pi\alpha/\beta_1)$ , in compressible flow with higher  $M_2$  is higher than that in incompressible flow.

5) Comparing Figs. 4 and 5 for  $V_2/V_1 = 1.5$ , it may be concluded that high jet temperature has detrimental effects on lift as it would reduce the dynamic pressure. At  $T_2/T_1 = 3.0$  and  $V_2/V_1 = 1.5$ ,  $c_l$  is less than the uniform flow value because  $\lambda_{12}$  is now positive. Examining Figs. 3 and 4 for  $V_2/V_1 = 3.0$ , it is also seen that the lift augmentation for  $T_2/T_1 = 3.0$  and  $M_1 = 0.4$  is much less than that in the incompressible flow when the airfoil is close to the jet boundary. Therefore, wind-tunnel tests of wing-jet interaction with cold jet may overestimate the lift unless

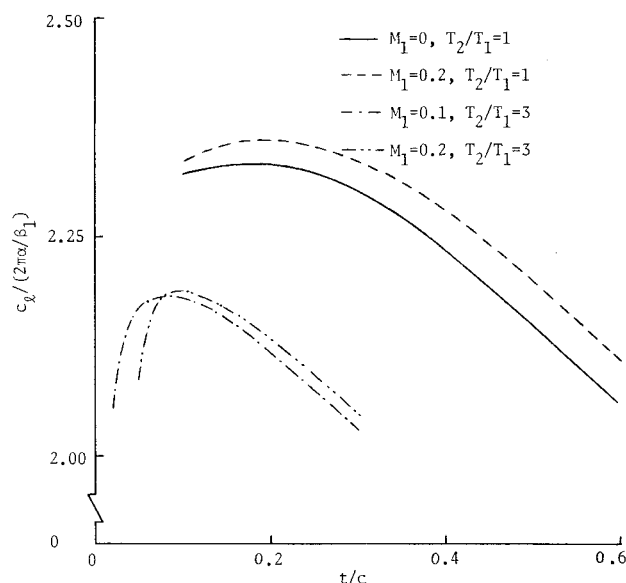


Fig. 6 Variation of lift augmentation with jet thickness,  $M_1$  and  $T_2/T_1$  at  $c_T = 2.095$  for the upper surface blowing configuration.

all flow parameters, in particular  $\lambda_{12}$ , are correctly simulated.

6) Consider the following observations for  $h = 0$ . a) With negative  $\lambda_{12}$ , i.e., the lift is increased over the uniform flow value, diffraction terms in Eq. (8) are to decrease the lift. These diffraction terms become unimportant as the jet thickness is increased. b) The lift is always increased when  $V_2/V_1$  is increased.

Keeping these two facts (6a and b) in mind, now consider the case with a given amount of thrust. As the jet thickness is increased, the diffraction becomes less important so that the lift is increased, while the decrease in velocity ratio because of thicker jet is to decrease the lift. On the other hand, as the jet thickness is decreased, the above two effects reverse the trend. In the limit as  $t \rightarrow 0$ , the diffraction terms are so important that they exactly cancel the reflection effect so that the uniform-flow results are obtained. This can be shown by summing the coefficients inside the brackets in Eq. (8). This gives  $f = 1 + \lambda_{12} + \delta_{12}\delta_{21}\lambda_{21}(1 + \lambda_{21}^2 + \lambda_{21}^4 + \dots) = 1 + \lambda_{12} + \delta_{12}\delta_{21}\lambda_{21}/(1 - \lambda_{21}^2)$ . However, for any  $\beta_1$  and  $\beta_2$ , it can be easily shown that  $\lambda_{21} = -\lambda_{12}$  and  $\delta_{12}\delta_{21} = 1 - \lambda_{21}^2$ . It follows that  $f = 1 + \lambda_{12} + \lambda_{21} = 1$  independent of the velocity ratio. Therefore, as the jet thickness is increased from zero, the lift will be increased. Eventually, the lift will be decreased after reaching a maximum value because of the low velocity ratio associated with the large jet thickness. An optimum jet thickness is seen to exist. For the purpose of numerically computing the optimum jet thickness, a thrust coefficient  $c_T$  of 2.095 per unit span is assumed, a value taken directly from Ref. 5. This thrust coefficient will be defined as the amount of thrust divided by the jet thickness and the freestream dynamic pressure. By the momentum theory, the velocity ratio then depends on the jet thickness in accordance with the relation:

$$\frac{V_2}{V_1} = \frac{1}{2} \left[ 1 + \left( 1 + \frac{2C_T}{(\rho_2/\rho_1)(t/c)} \right)^{1/2} \right] \quad (10)$$

The results of computation are presented in Fig. 6. It is seen that an optimum jet thickness does exist. For  $T_2/T_1 = 1.0$ , the optimum thickness ratio  $t/c$  lies between 0.175 and 0.2, approximately independent of the Mach number. On the other hand, for  $T_2/T_1 = 3.0$ , the optimum  $t/c$  becomes 0.1.

## References

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## Evaluation of Drag Integral Using Cubic Splines

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### Introduction

THE well-known wave drag integral<sup>1</sup> which expresses the drag of suitably slender configurations in terms of an area distribution  $S(x)$  can be written

$$I = -\frac{1}{2\pi} \int_0^1 \int_0^1 S''(x) S''(y) \ln |x - y| dx dy \quad (1)$$

This integral has been studied extensively in the past, notably by Eminton<sup>2</sup> to whom goes credit for the most widely used practical method of evaluation, given only a discrete point data set of values of  $S(x_i)$ . For most engineering applications, the input data set is quite crude whether the values represent areas or some other physical quantity arising from different calculations to which  $I$  applies. Nevertheless,  $S(x)$  must be assumed to satisfy certain conditions, and the minimum necessary for Eq. (1) to be useful are:

$$\begin{aligned} S'(x) &\text{ is continuous in } (0 \leq x \leq 1) \\ S'(0) &= S'(1) = 0 \end{aligned} \quad (2)$$

For the evaluation of drag when these conditions are not satisfied (in particular when  $S'(x)$  is not continuous) more

involved formulas than Eq. (1) alone are required,<sup>3</sup> but the restrictions, Eq. (2), are commonly assumed in practice and are required by Eminton's method.

### Spline Techniques

With regard to the use of cubic (or other) splines in practical engineering, it is the authors' experience that all too often the initial enthusiasm is rapidly damped by the necessity for providing end conditions beyond mere point values in order to solve the usual tridiagonal matrix for the point second derivatives. If these extra conditions are not known with the same degree of precision as the point values of the function itself, then the spline formulation is no better than other simpler means of ad hoc interpolation. Many engineering applications start with poor quality input information, and under these circumstances splines are just another tool, not a panacea.

However, the conditions (2) are ready made for a spline assumption since the end derivatives are given exactly. Therefore, it was decided to test the accuracy of a spline method of evaluation of  $I$  by fitting the area distribution with a cubic spline using a standard subroutine for rapid solution of the usual tridiagonal matrix—essentially by Gaussian elimination. Such a method, it was felt, might be quicker than Eminton's and would not require the inversion of a full matrix and so might not be subject to the usual problems arising from large full matrix operations (e.g., large computer core requirements).

This idea, obvious as it is, had not attracted much attention until recently. Halfway through the runs described in this Note, the work of V. V. Shanbhag<sup>4</sup> came to the authors' attention; but it was decided to publish these results anyway as a further source of comparison cases.

It should be noted that the Eminton method has a design aspect in the sense that the eventual interpolation provides a body of minimum drag subject to the given constraint of having specified areas at certain  $x$  stations. Such a facility cannot necessarily be claimed for the spline method, but the purpose of this Note is merely to compare some evaluations. A more comprehensive view of these methods must be left to the practicing designers in this field.

### Calculation Procedure

If  $S(x)$  is given as a polynomial in  $x$  subject to conditions (2), then it is easy to evaluate  $I$  analytically in terms of the numbers

$$I_{r,s} = -\frac{1}{2\pi} \int_0^1 \int_0^1 x^r y^s \ln |x - y| dx dy$$

These have been computed at Douglas Aircraft Co. using the IBM 370/165 system and stored and tabulated (for quick hand estimates). By using these numbers an exact solution is readily available to provide a standard for comparison between the Eminton and spline methods. The Eminton calculations were obtained from a standard production subroutine using point values of  $S(x)$  as input. For the spline calculations  $S''(x)$  is piecewise linear and so with some tedious but minor manipulations  $I$  can be expressed in various condensed forms. It appears that the nearest involves fourth differences of  $S_j = S(x_j)$ , but from a computational accuracy point of view, the formula actually used had more of an "influence function" character, viz.:

$$I = \frac{3a_m a_1}{4\pi} - \frac{a_m}{\pi} \sum_{j=1}^{m-1} b_j [W_{j,m}] - \frac{a_1}{\pi} \sum_{j=1}^{m-1} b_j [W_{j,1}] - \frac{1}{2\pi} \sum_{k=1}^{m-1} \sum_{j=1}^{m-1} b_k b_j \langle Z_{j,k} \rangle$$

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